

# Fault Diagnosis of Models With Constraints

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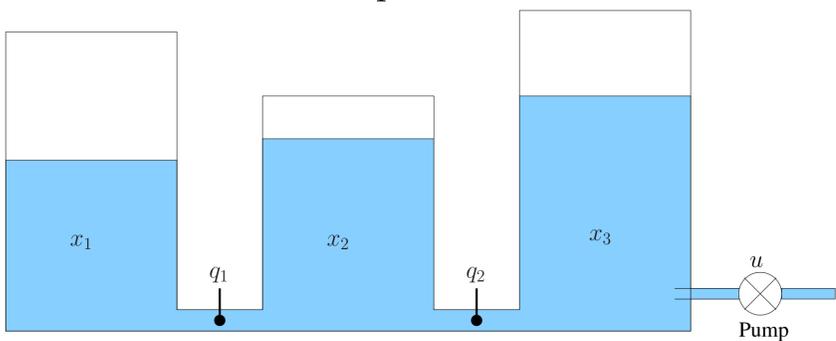
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## Summary

Structural analysis is a standard tool to identify sub-models that can be used to design model based diagnostic tests. Structural approaches typically operate on models described by a set of equations. This work extends such methods to be able to handle models with constraints, e.g. inequality constraints on state variables.

## Three Tank System

The following water tank system will be used to illustrate the basic concepts



There are two sensors measuring the level  $x_1$  and the flow  $q_1$ . Consider the following model of the system:

$$\begin{aligned} e_1 : \dot{x}_1 &= -q_1, & e_4 : q_1 &= x_1 - x_2, & e_6 : y_1 &= x_1 \\ e_2 : \dot{x}_2 &= q_1 - q_2, & e_5 : q_2 &= x_2 - x_3, & e_7 : y_2 &= q_1 \\ e_3 : \dot{x}_3 &= q_2 - u \end{aligned}$$

Four tests can be found using conventional structural methods:

$$\begin{aligned} \dot{y}_1 + y_2 &= 0, & \ddot{y}_1 + 2\dot{y}_1 - \ddot{y}_2 - 3\dot{y}_2 - y_2 + u &= 0 \\ y_1^{(3)} + 4\ddot{y}_1 + 3\dot{y}_1 + u &= 0, & \ddot{y}_2 + 3\dot{y}_2 + 3y_2 - u &= 0 \end{aligned}$$

These tests were derived by first identifying the smallest subsets with one redundant equation, e.g.,  $\{e_1, e_6, e_7\}$ , and then eliminating the unknown variables.

## Constraints

The model can be extended by adding the constraints

$$c_1 : x_1 \in [0, h_1], \quad c_2 : x_2 \in [0, h_2], \quad c_3 : x_3 \in [0, h_3]$$

to the model.

## Trivial Examples

Two simple examples are used to illustrate how the constraints can be used to construct tests.

★ Equation  $e_6$  and constraint  $c_1$  give the obvious test

$$y_1 \in [0, h_1]$$

★ From  $e_4$  and  $e_7$  it follows that  $y_2 = x_1 - x_2$ , and using  $c_1$  and  $c_2$  the test

$$y_2 \in [-h_2, h_1]$$

is obtained.

## A Not so Trivial Example

The algorithm finds 16 more subsets of equations. For example, a less obvious set that can be used to construct a test is

$$\begin{aligned} e_2 : \dot{x}_2 &= q_1 - q_2, & e_4 : \dot{q}_1 &= \dot{x}_1 - \dot{x}_2, & c_2 : x_2 &\in [0, h_2] \\ e_4 : q_1 &= x_1 - x_2, & e_6 : \dot{y}_1 &= \dot{x}_1, & c_3 : x_3 &\in [0, h_3] \\ e_5 : q_2 &= x_2 - x_3, & e_7 : \dot{y}_2 &= \dot{q}_1 \\ e_6 : y_1 &= x_1 \end{aligned}$$

By eliminating  $x_1$ ,  $\dot{x}_1$ ,  $\dot{x}_2$ ,  $q_1$ ,  $q_2$ , and  $\dot{q}_1$  the relation  $\dot{y}_1 - \dot{y}_2 - y_1 = x_3 - 2x_2$  is obtained and the corresponding test is

$$\dot{y}_1 - \dot{y}_2 - y_1 \in [-2h_2, h_3]$$

## Main Results

The main results of the work can be summarized as:

- Structural characterization of the sought subsets.
- Development of an algorithm that finds all subsets.
- Derivation of the tests.

## References

- [1] Jan Åslund and Erik Frisk. Structural analysis for fault diagnosis of models with constraints *Proceedings of IFAC Safeprocess'09*, 384–389, 2009, Barcelona, Spain.